

# Extreme Weather Event Prediction

Enhancing weather forecasts

# Assignments

Keep working on your projects!

Poll on project work day

Homework #4 - Dengue fever cases

**Due Monday the 17th by midnight**

# Climate change in the news

# Climate change in the news

PRESS RELEASE

## H&M MOVE PARTNERS WITH LANZATECH TO LAUNCH CAPSULE COLLECTION USING CAPTURED CARBON EMISSIONS

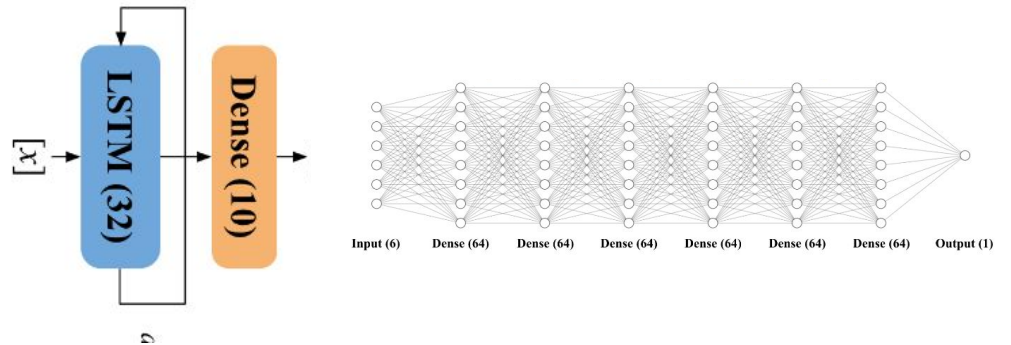
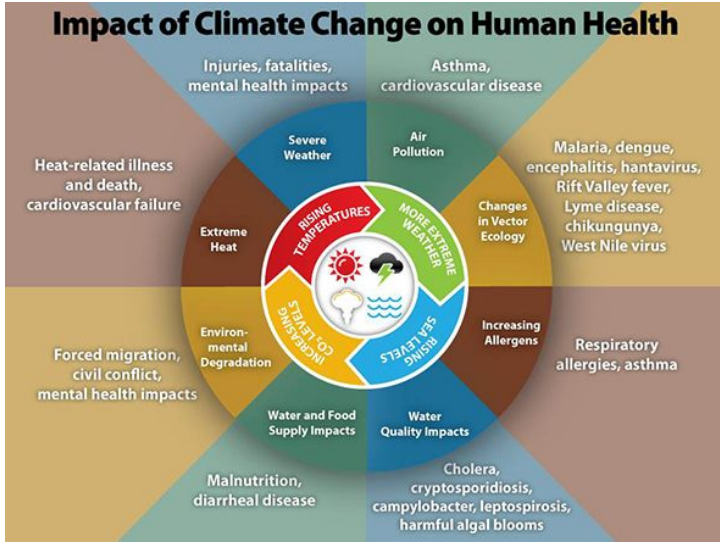
This is the stuff of science fiction: LanzaTech diverts carbon emissions heading for the atmosphere, traps them, and turns them into thread. In a leap towards innovating sportswear, H&M Move partners with the breakthrough material science company for a drop arriving at [hm.com/move](https://www.hm.com/move) on April 6.



Using three simple steps, LanzaTech captures carbon emissions from steel mills, traps them in bioreactors and converts them into the same building blocks that conventional polyester is made of. This revolutionary solution helps reduce pollution and limits the use of virgin fossil resources needed to make new products.

H&M Move's upcoming three-piece drop for women includes a jumpsuit, a top and a pair of tights, partly made of LanzaTech CarbonSmart™ polyester with a DryMove™ finish. The sleek, all-black garments draw on the contemporary athluxury movement and feature contrasting seams and creative cut-outs.

# Recap




# Recap



Prof. Laure Zanna

# Geophysical Research Letters\*

Research Letter |  [Free Access](#)

## Data-Driven Equation Discovery of Ocean Mesoscale Closures

Laure Zanna  Thomas Bolton

First published: 06 August 2020 | <https://doi.org/10.1029/2020GL088376> | Citations: 55

 SECTIONS

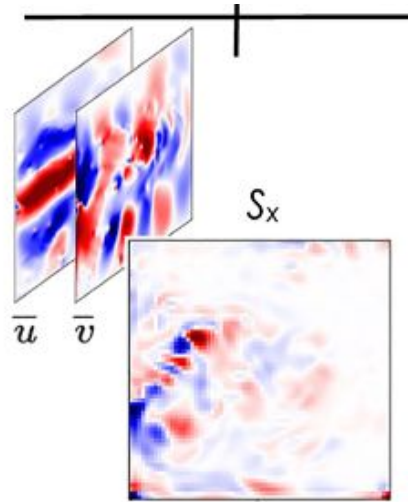
 PDF

 TOOLS

 SHARE

<https://agupubs.onlinelibrary.wiley.com/doi/10.1029/2020GL088376>

Goal: find an equation that relates small scale physics to large scale, in order to correct coarse-grain simulations



Diagnose  $\mathbf{S}$  from  
the high-resolution  
model velocities



# Plan: Use “relevance vector machine” regression

- “Equation discovery” - provide a list of terms and it will find weights for each term
- Requires some ‘hand-engineering’
- Produces more interpretable result
- some memory constraints

“filtered velocities using up to second order for both spatial derivatives and polynomial products”

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**Basis functions:**

$$\text{Divergence: } \sigma = \overline{\nabla} \cdot \overline{\mathbf{u}}$$

$$\text{Vorticity: } \zeta = \overline{\nabla} \times \overline{\mathbf{u}}$$

$$\text{Shearing Deformation: } D = \frac{\partial \overline{u}}{\partial y} + \frac{\partial \overline{v}}{\partial x}$$

$$\text{Stretching Deformation: } \tilde{D} = \frac{\partial \overline{u}}{\partial x} - \frac{\partial \overline{v}}{\partial y}$$

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Library of functions  
as divergence of flux:  
 $\phi_i(\overline{u}, \overline{v})$

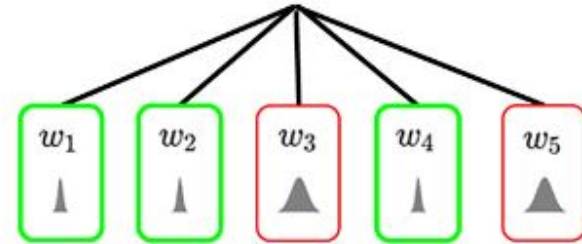
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# RVM regression

- Gaussian prior distributions for each regression weight
- Allows for a measure of uncertainty
- Terms are iteratively pruned from the equation if width of the distribution is too large
- This uncertainty threshold is the only parameter that requires setting

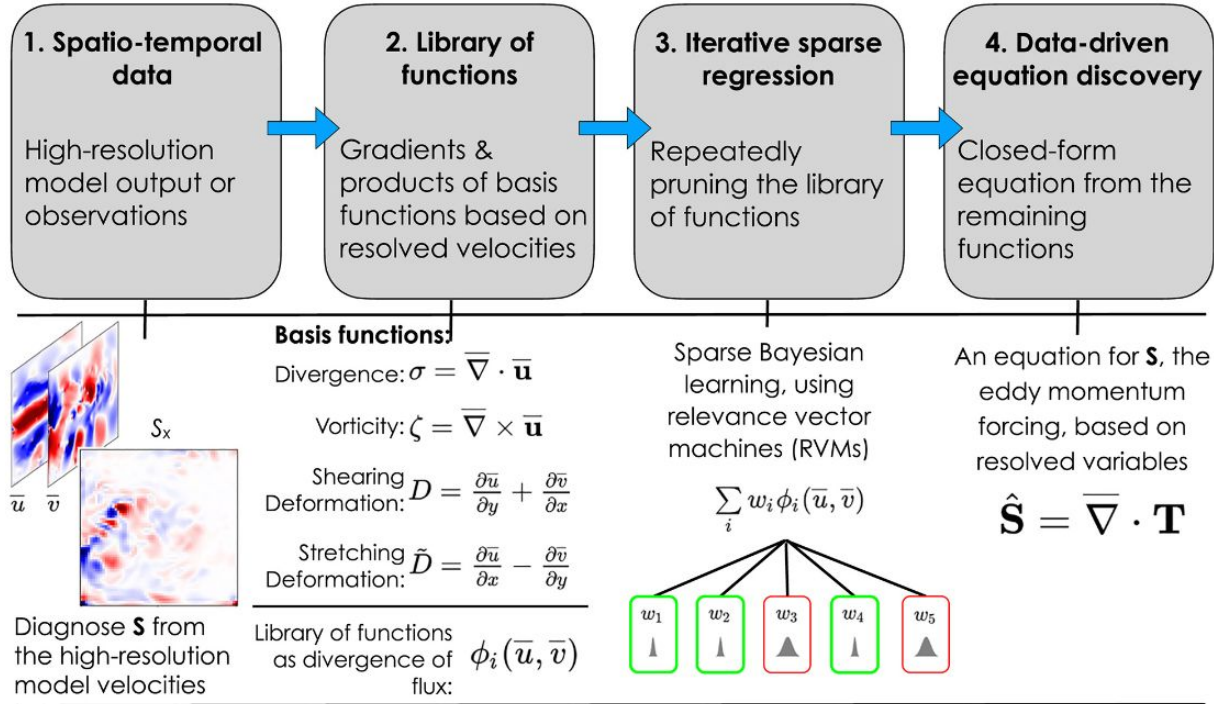
Sparse Bayesian learning, using relevance vector machines (RVMs)

$$\sum_i w_i \phi_i(\bar{u}, \bar{v})$$



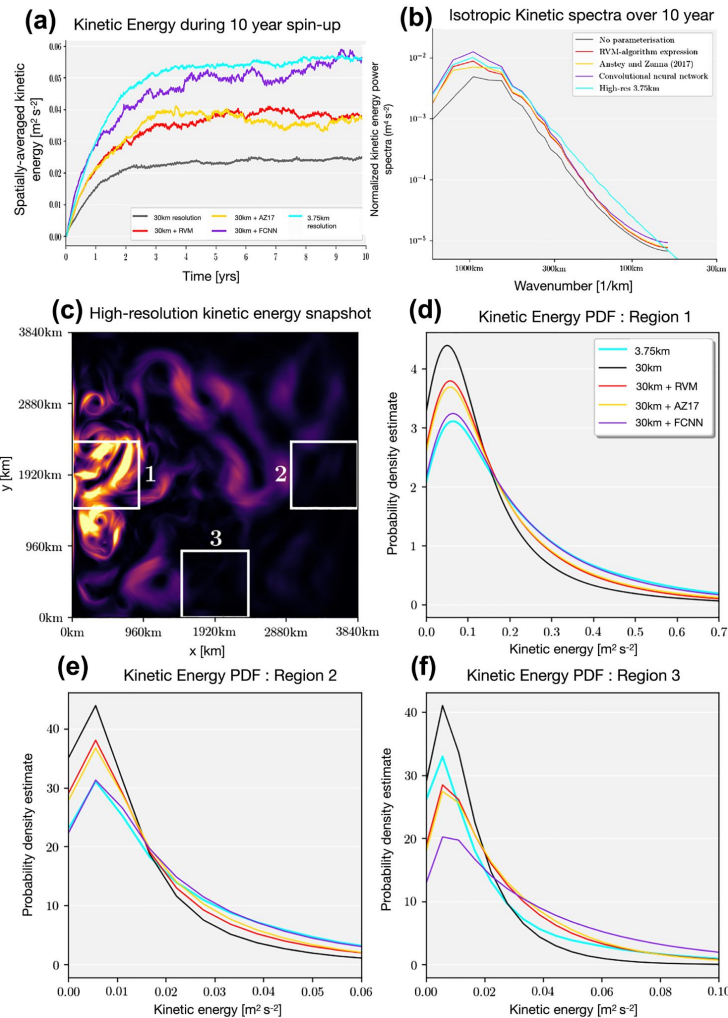
# Overall process

## (a) Relevance Vector Machine Schematic

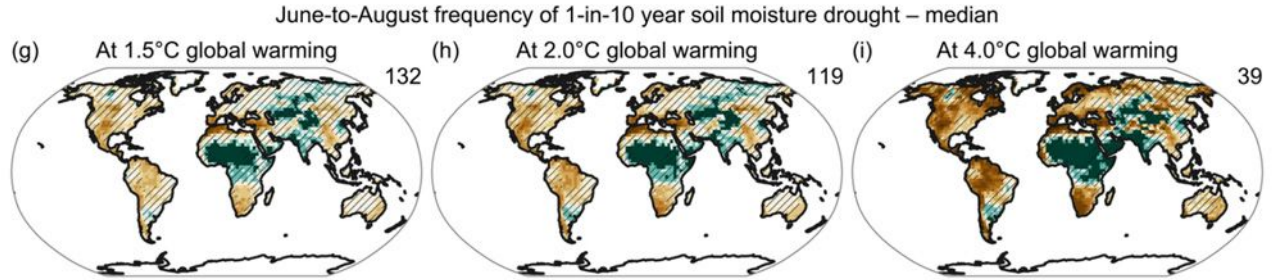


# Results

RVM versus convolutional neural network approach has some tradeoffs

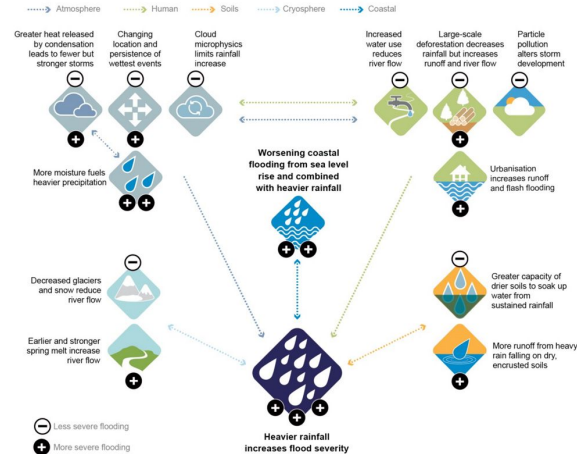


# Extreme weather events will become more common

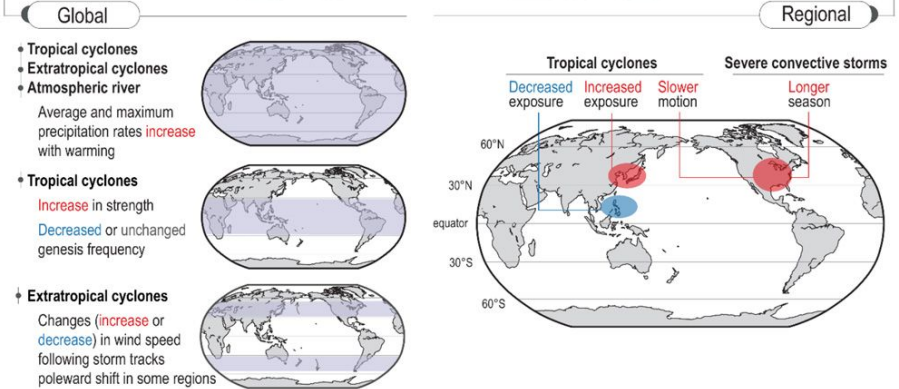


## FAQ 8.2: Causes of more severe floods from climate change

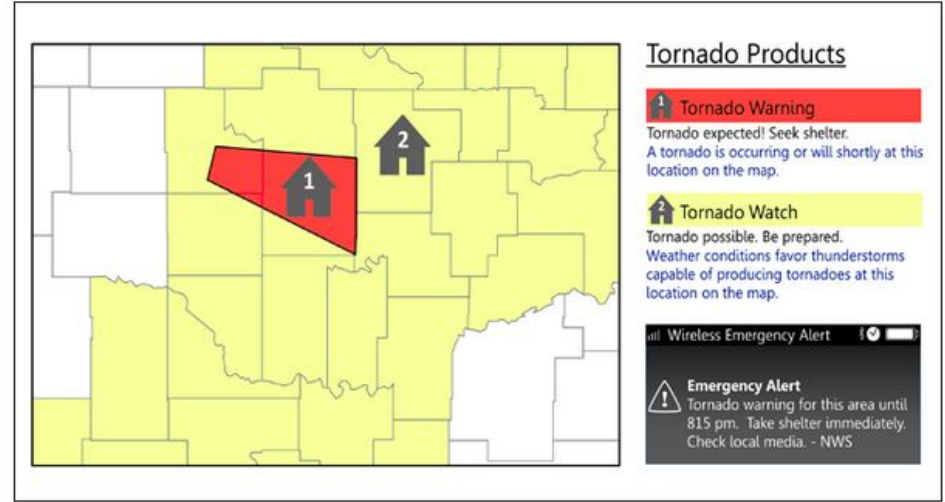
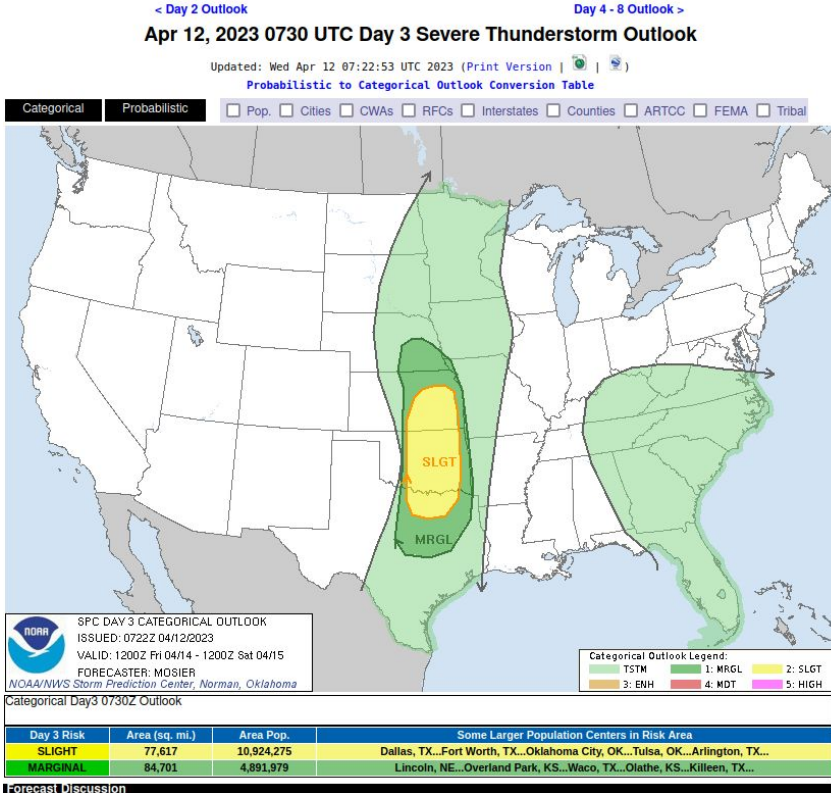
Flooding presents a hazard but the link between rainfall and flooding is not simple. While the largest flooding events can be expected to worsen, flood occurrence may decrease in some regions.



## Changes in storms with increasing global warming



# Importance of prediction



Prediction and alert systems give people time to prepare. The earlier the better, but accuracy matters too.

# Challenge of weather prediction





# How predictions are done

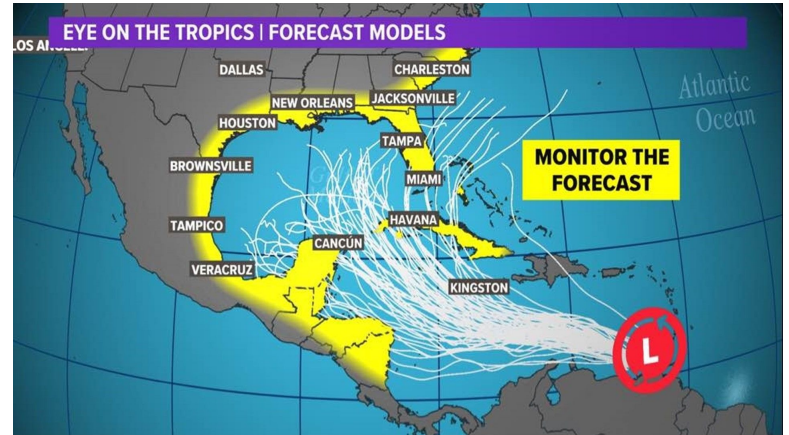
Numerical simulations predict future weather using physics and dynamics to mathematically describe the atmosphere's behavior

Models cover points over a large area, from the Earth's surface to the top of the atmosphere.

They start with current weather data and run forward

Data is gathered from weather balloons launched around the globe twice each day, in addition to measurements from satellites, aircraft, ships, temperature profilers and surface weather stations.

[www.nssl.noaa.gov](http://www.nssl.noaa.gov)



Ensembles based on different initial conditions or model



# Paper Deep Dive

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## Deep Learning Models for Predicting Wildfires from Historical Remote-Sensing Data

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**Fantine Huot**<sup>1,2</sup>      **R. Lily Hu**<sup>1</sup>      **Matthias Ihme**<sup>1,2</sup>      **Qing Wang**<sup>1</sup>  
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**John Burge**<sup>1</sup>      **Tianjian Lu**<sup>1</sup>      **Jason Hickey**<sup>1</sup>      **Yi-Fan Chen**<sup>1</sup>      **John Anderson**<sup>1</sup>

<sup>1</sup>Google Research

<sup>2</sup>Stanford University

<https://arxiv.org/pdf/2010.07445.pdf>

# Motivation

In 2019, 775,000 residences across the United States were flagged as at an “extreme” risk of destructive wildfire, amounting to an estimated reconstruction cost value of \$220 billion dollars.

Wildland fires have a significant impact on the global climate, representing 8 billion tons or 10% of global CO2 emissions per year.

Furthermore, the health impact due to wildfire aerosols is estimated at 300,000 premature deaths globally per year.

***There is a real need for novel wildfire warning and prediction technologies that enable better fire management, mitigation, and evacuation decisions.***

# Goal

Historically, wildfire likelihood has been based on fire behavior modeling across *simulations* by varying feature parameters (e.g. weather, topography) that contribute to the probability of a fire occurring.

**Goal:** Predict wildfire burning (over the next few days) in a specific location using machine learning

# Brainstorm

What kind of data would you want to have to be able to approach this problem?

What kind of methods would you apply?

How would you measure success?

What difficulties might you face?

# Data

Aggregated nearly a decade of satellite observations, combining historical wildfire, terrain, vegetation, and weather data to train a deep learning model.

Need data that has

- historical record for training
- high spatial resolution and regular updates for future prediction

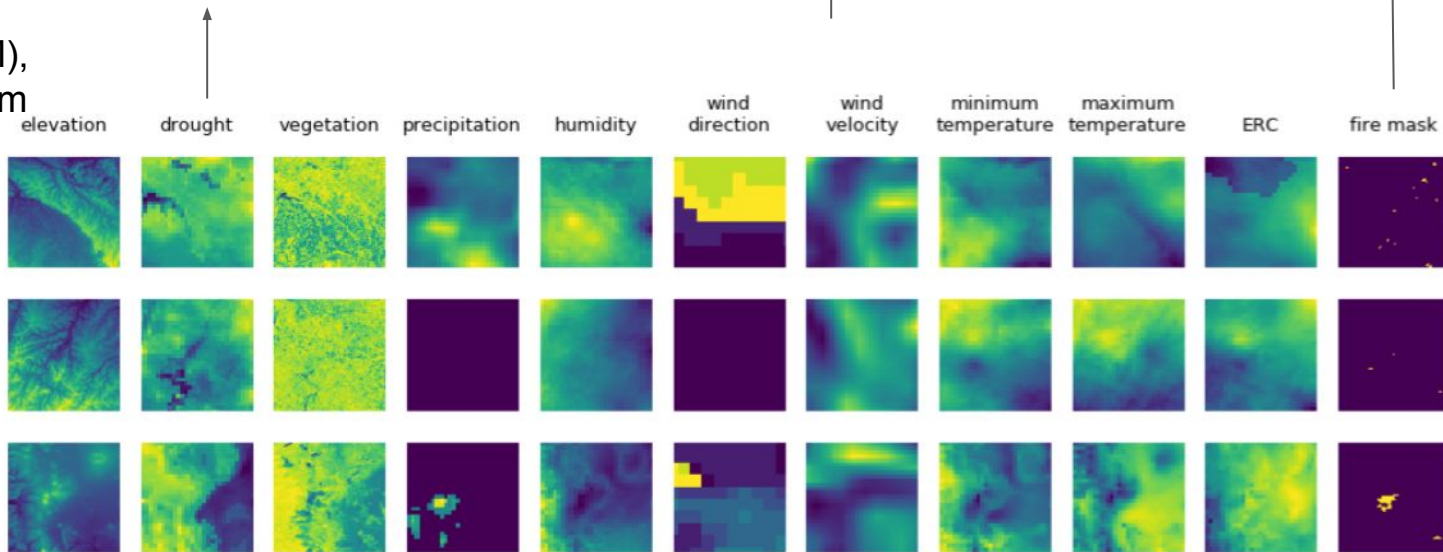
# Data

collection of drought indices derived from the GRIDMET dataset, sampled at 4 km resolution every 5 days since 1979

Collection of daily surface fields of temperature, precipitation, winds, and humidity at 4 km resolution since 1979

daily fire mask composites at 1 km resolution since 2000

Shuttle Radar Topography Mission (SRTM), sampled at 30 m resolution



a collection of vegetation indices sampled at 500 m resolution every 8 days since 2012

# Data problem

Different spatial resolutions, temporal resolutions, and temporal extents.

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Different spatial resolutions, temporal resolutions, and temporal extents.

The data is resampled to 1 km resolution, the resolution of the labels. From this data we sample  $128 \times 128$  tiles at 1km resolution. The region of study is restricted to the contiguous United States from 2012 to 2020.

Temporal resolution ??



# Framing the problem

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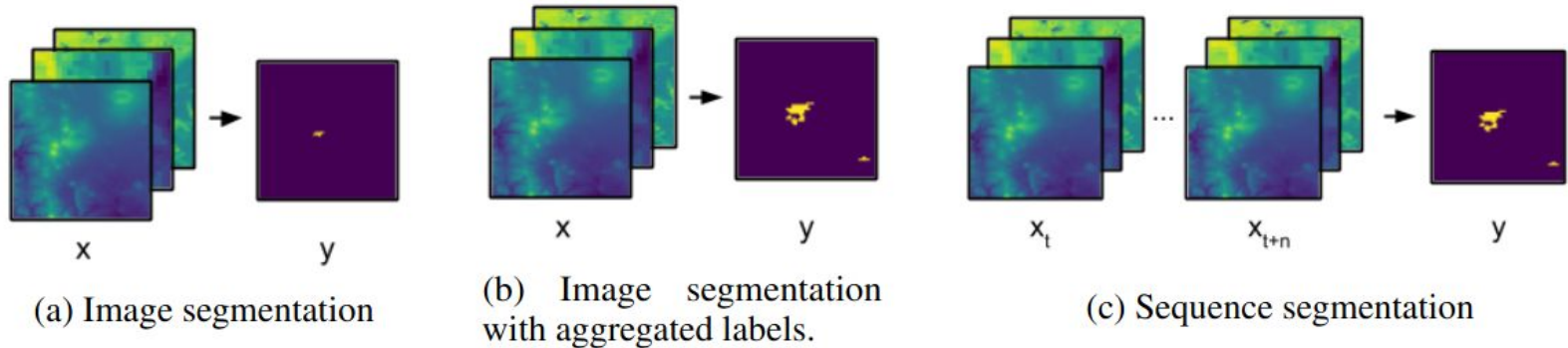
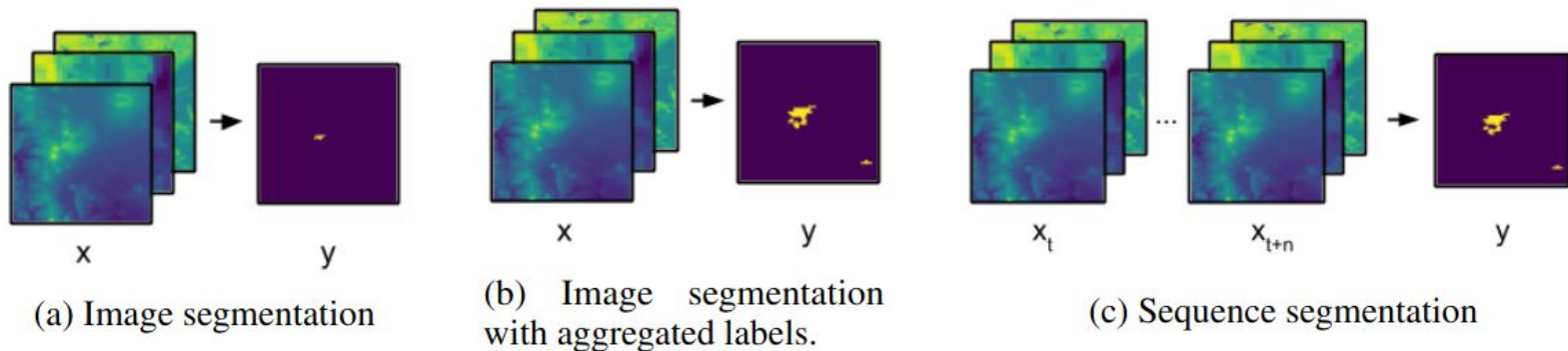


Figure 2: The fire likelihood estimation problem is framed as three machine learning tasks: (a) an image segmentation problem, where the input features are taken one day prior to a fire. (b) an image segmentation problem with aggregated fire masks, where the input features are taken one day prior to a fire, and the fire masks are aggregated over a week to capture the total burn area, and (c) a sequence segmentation problem. The input features are arranged in week-long sequences to capture the time-component of the data.

“segmentation”?

# Framing the problem

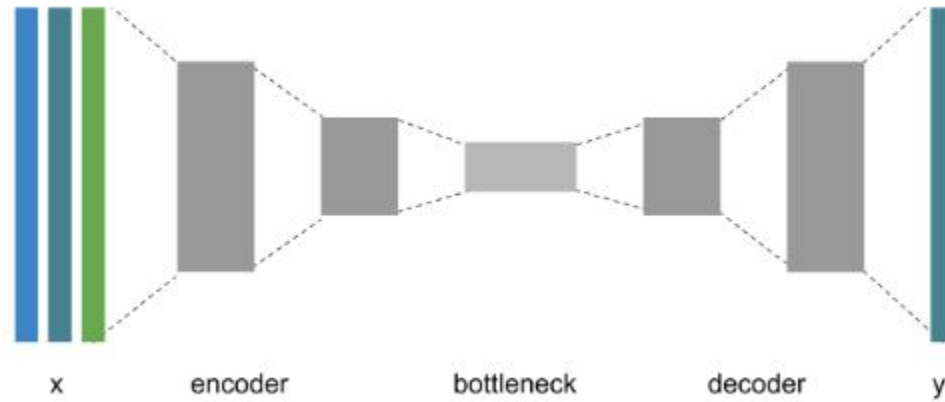


The dataset for experiment 1 has about 110,000 samples in the training set, 10,000 samples in the validation set, and 10,000 samples in the testing set.

The data sets for experiments 2 and 3 have about 35,000 samples in the training set, 5,000 in the validation set, and 5,000 in the testing set.

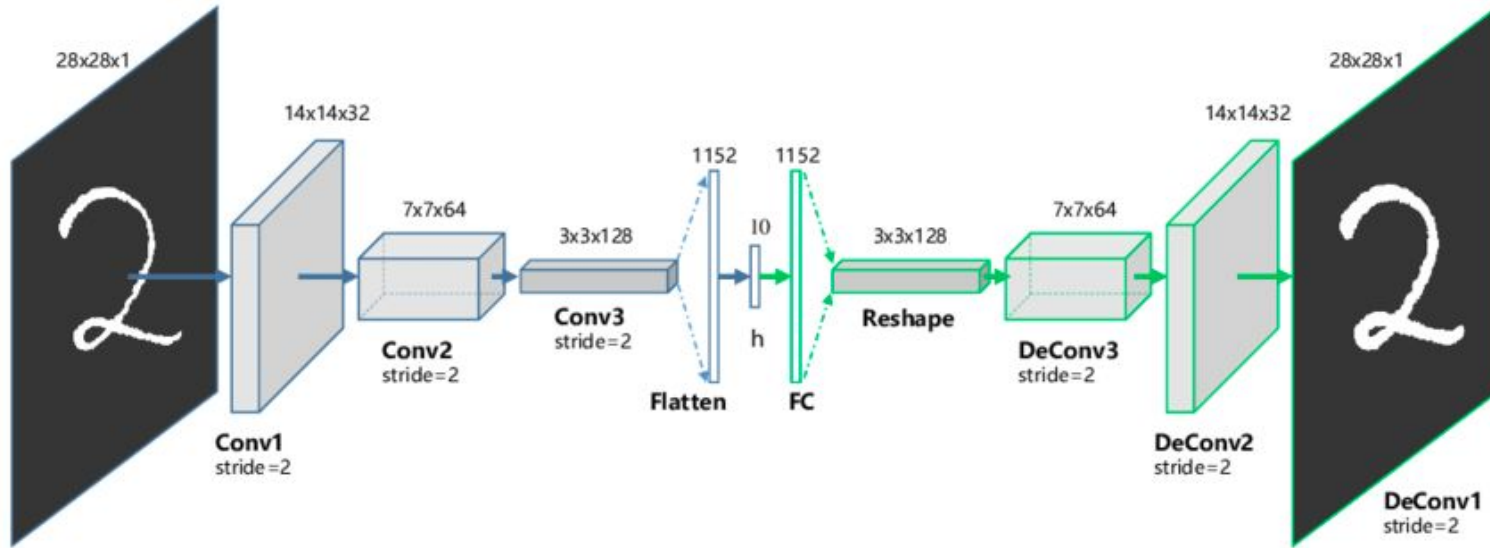
Model(s)

# Model(s)



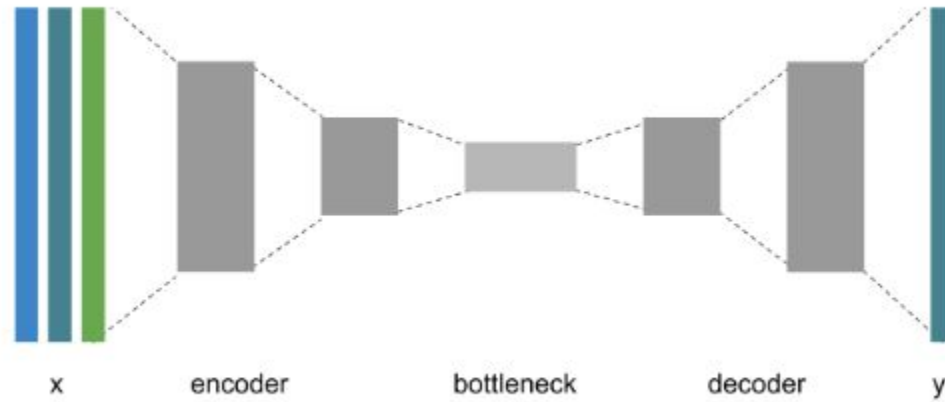
Convolutional “auto”encoder

# What an autoencoder really is



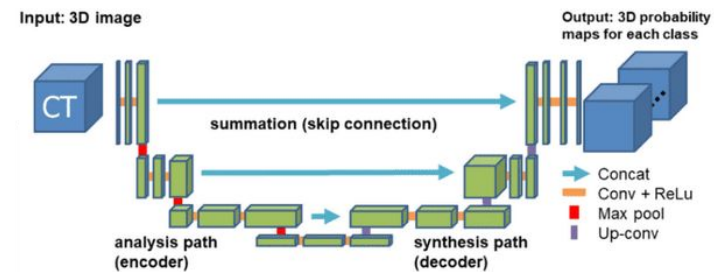
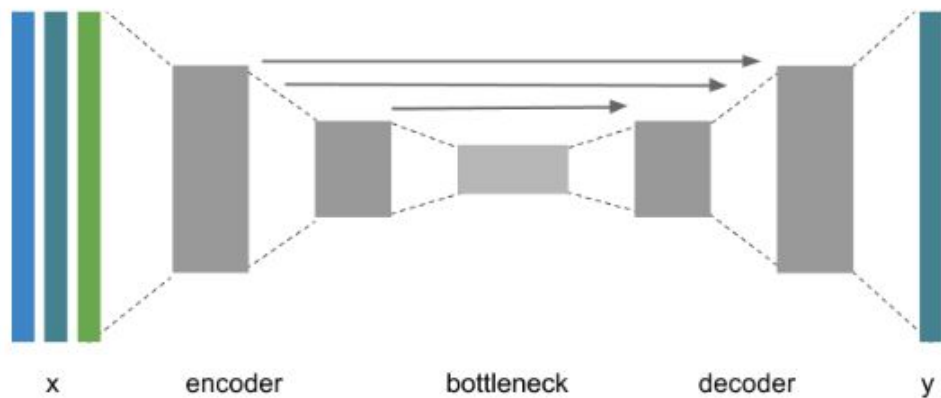
In a true autoencoder, the model is trained to reproduce its input

# Model(s)



Convolutional ~~“auto”encoder~~ encoder/decoder

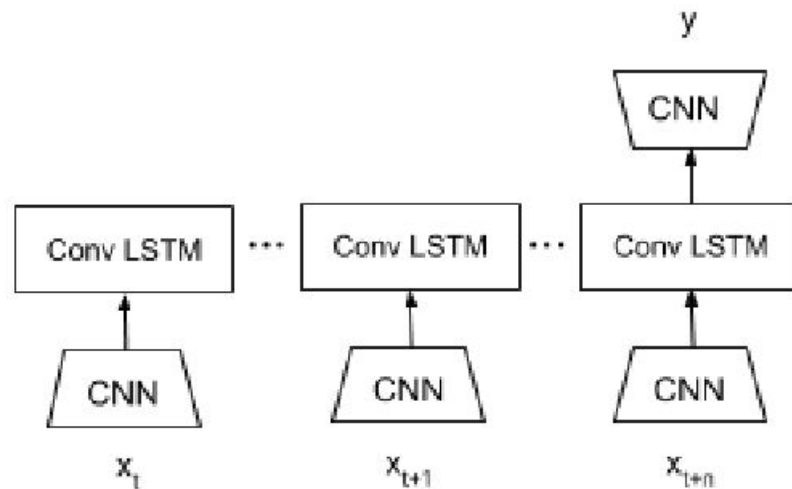
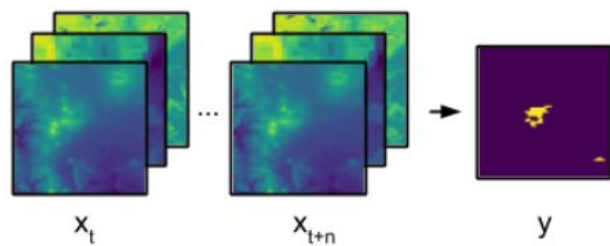
# Model(s)



## Convolutional U-net

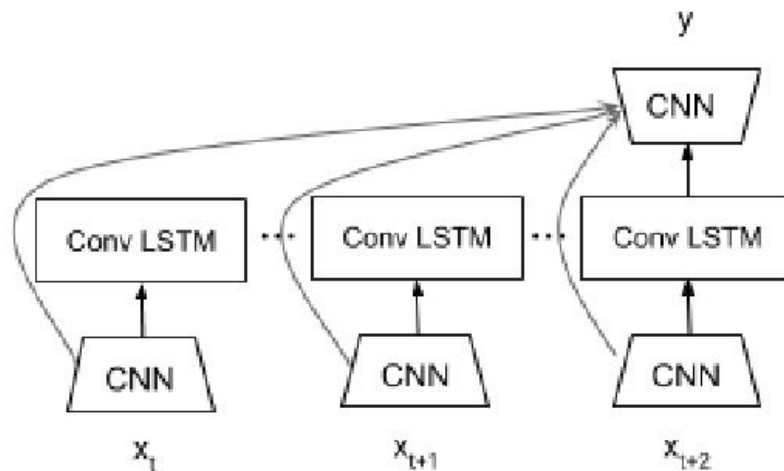
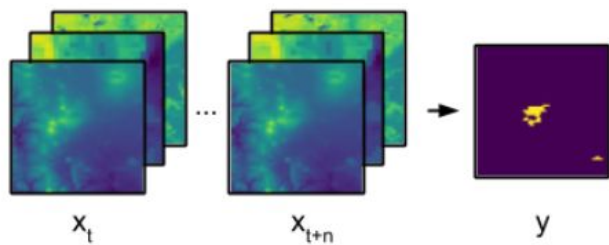


# Model(s)



## Convolutional LSTM

# Model(s)



Convolutional U-net LSTM

# Training problem!

The vast majority of pixels do not have fire.

# Training problem!

The vast majority of pixels do not have fire.

Use “weighted cross-entropy loss” to overcome the class imbalance.

$$CE = -(y \log \hat{y} + (1 - y) \log(1 - \hat{y}))$$

$$WCE = -(\beta y \log(\hat{y}) + (1 - y) \log(1 - \hat{y}))$$

true class  
label

model  
prediction

# Training

- Hyperparameters explored via grid search:
  - Model depth
  - Number of filters
  - Batch size
  - Learning rate
  - Beta, weight of positive class

Evaluated on validation set according to AUC

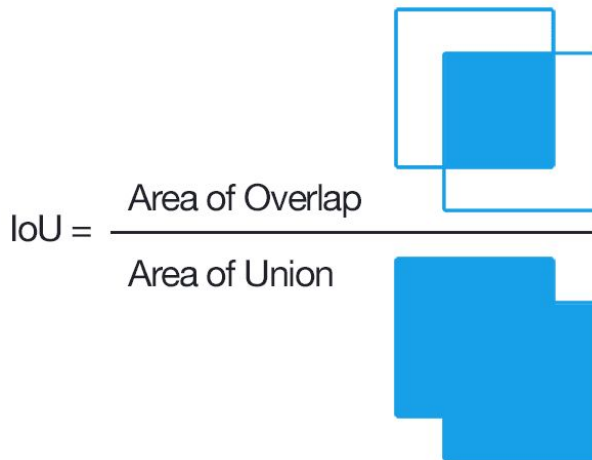
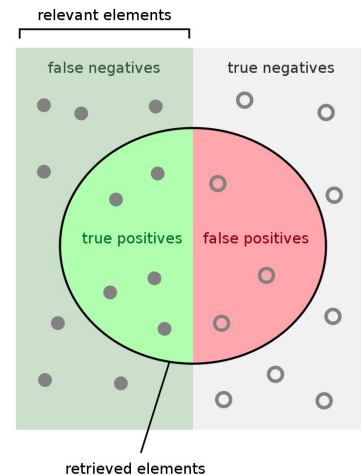
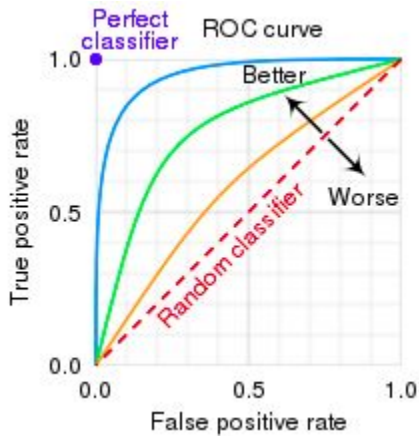
# Evaluation

Area under the ROC

Precision

Recall

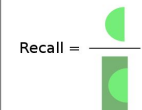
Intersection over Union



How many retrieved items are relevant?



How many relevant items are retrieved?



# Results

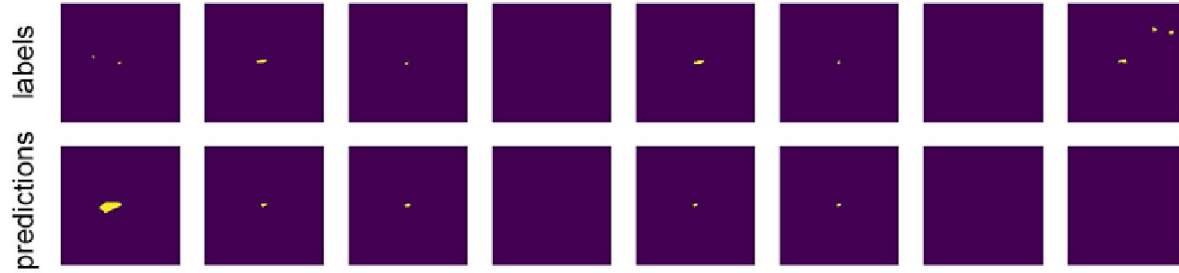
Experiment	Model
Daily Segmentation	Autoencoder U-Net
Aggregated Segmentation	Autoencoder U-Net
Aggregated Segmentation with Sequential input	Autoencoder LSTM U-Net LSTM

# Results

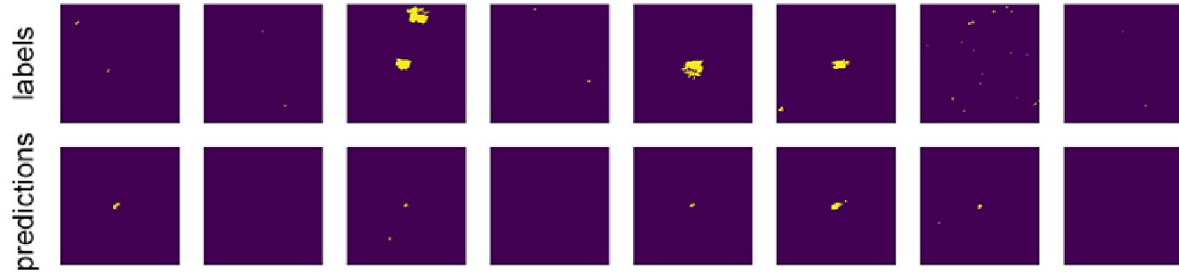
Experiment	Model	AUC	Precision	Recall	IoU
Daily Segmentation	Autoencoder	<b>0.83</b>	0.53	0.12	0.52
	U-Net	0.72	0.29	0.08	0.52
Aggregated Segmentation	Autoencoder	0.55	0.30	0.05	0.50
	U-Net	0.54	0.29	0.05	0.50
Aggregated Segmentation with Sequential input	Autoencoder LSTM	0.58	0.49	0.05	0.51
	U-Net LSTM	0.60	0.48	0.03	0.50



# Results



(a) Image segmentation results from the autoencoder model on the test data with daily active fire labels.



(b) Image segmentation results from the autoencoder LSTM model on the test data with aggregated fire labels.

“The low values are indicative of misclassified pixels at the segmentation boundary between fire and non-fire, or very small fires not being detected, *and thus not representative of the overall performance of the models to predict the presence of fire.*”

“Even without exact segmentation predictions, identifying these regions ahead of time would allow forestry management to allocate resources to specific target regions.”

# Results

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“We observed more severe overfitting with the aggregated segmentation map, likely due to the a smaller dataset size.”

“These experiments would likely improve from data augmentation techniques, for example, by adding noise to the input features. Another idea would be to increase the time span of the data sets, but this would involve combining multiple data sources for some of the input variables due to limited temporal coverage – many satellites started collecting data only within the past few years. Another future step is to expand these experiments beyond the United States to a global scale.”

# Framing the problem

“Identifying regions that have high **likelihood** for wildfires is a key component of land and forestry management and disaster preparedness.”

“In particular, assessing the fire **likelihood** – the **probability** of wildfire burning in a specific location – would provide valuable insight for forestry and land management, disaster preparedness, and early-warning system”

“A use case for models trained on this compiled data is to predict the **likelihood** of fires given recent remote sensing data.”

*“Positive events are only labeled when there are actual fires, but the dataset also contains tiles with high fire likelihood that did not have actual fires, such as days before fires or neighboring areas that did not catch fire because firefighters intervened”*

## 5 Conclusions

We demonstrate the potential of deep learning approaches for estimating the fire likelihood from remote-sensing data. We create a data set by aggregating nearly a decade of remote-sensing data, combining features including weather, drought, topography, and vegetation, with historical fire records. Our trained models can successfully distinguish between fire and non-fire conditions. Going forward, this data-driven approach could be valuable for wildfire risk estimation, and could be incorporated into wildfire warning and prediction technologies to enable better fire management, mitigation, and evacuation decisions. Beyond the wildfire likelihood problem, the described workflow and methodology could be expanded to other problems such as estimating the likelihood of regions to droughts, hurricanes, and other phenomena from historical remote-sensing data.

## Further resources

<https://www.quantamagazine.org/machine-scientists-distill-the-laws-of-physics-from-raw-data-20220510/>

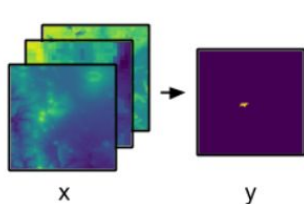
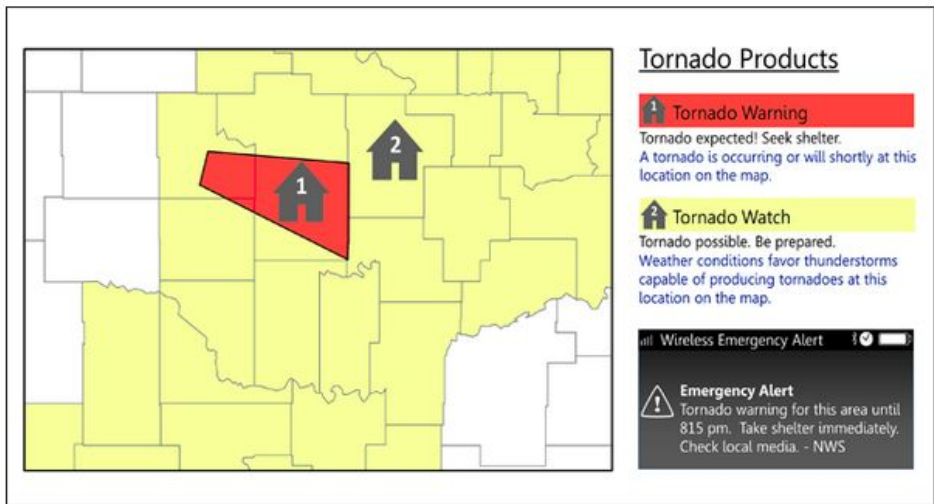
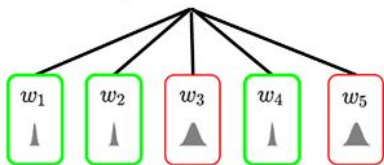
Why rain is hard to predict (DeepMind)

<https://www.youtube.com/watch?v=snCo0Z0dt-k>

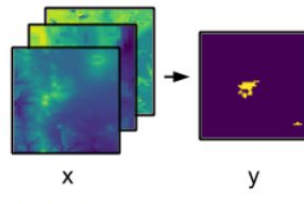
# Summary

Sparse Bayesian learning, using relevance vector machines (RVMs)

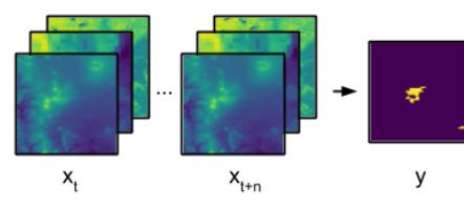
$$\sum_i w_i \phi_i(\bar{u}, \bar{v})$$



(a) Image segmentation



(b) Image segmentation with aggregated labels.



(c) Sequence segmentation